

EVCBM Dual DuctModbus Communication Module User Guide









Introduction

The EVCBM Dual Duct Modbus Communication Module User Guide provides information for using Neptronic[®] communication feature. The controller uses Modbus communication protocol over serial line in the RTU mode and provides a Modbus network interface between client devices and Neptronic EVCBM Dual Duct devices.

The EVCBM Dual Duct Modbus Guide assumes that you are familiar with Modbus terminology.

The following are the requirements for Modbus:

- Data Model. The EVCBM Modbus server data model uses only the Holding Registers table.
- Function Codes. The EVCBM Modbus server supports a limited function codes subset comprising:
 - Read Holding Registers (0x03)
 - Write Single Register (0x06)
 - Write Multiple Registers (0x10)
- Exception Responses. The EVCBM Modbus server supports the following exception codes:
 - Illegal data address
 - Illegal data value
 - Slave device busy
- Serial Line. The EVCBM Modbus over serial line uses RTU transmission mode over a two-wire configuration RS485 (EIA/TIA-485 standard) physical layer.
 - The physical layer can use fixed baud rate selection or automatic baud rate detection (default) as per the **Modbus Auto Baud Rate** device menu item or holding register index 1.
 - The supported baud rates are 9600, 19200, 38400, and 57600.
 - The physical layer also supports variable parity control and stop bit configuration as per the Modbus Comport Config device menu item or holding register index 2.
 - In auto baud rate configuration, if the device detects only consecutive bad frames (2 or more) for one second with any given baud rate, it will reinitialize itself to the next baud rate.
- Addressing. The EVCBM device only answers at the following address:
 - o The device's unique address (1 to 246) that can be set through the device menu or through holding register index 0.



Holding Registers Table

Table Glossary

Name	Description	Name	Description
W	Writable Register	ASCII	For registers containing ASCII (8-bit) characters
RO	Read Only Register	MSB	Most Significant Byte
Unsigned	Values from 0 to 65,535, unless otherwise specified	LSB	Least Significant Byte
Signed	Values from -32,768 to 32,767, unless otherwise specified	MSW	Most Significant Word
Bit String	Registers with multiple values using bit mask (example, flags)	LSW	Least Significant Word

Holding Register Table

Register Index	Description	Data Type	Range	Writable
4000 0	Modbus Address and Product Type.	Unsigned	MSB = Product type (e.g. 111 for EVCB) LSB = Modbus Address (e.g. 1-246)	W
4000 1	MSTP Baud Rate.	Unsigned Scale 100	0, 9600, 19200, 38400, or 57600 0 = Auto Baud Rate Detection Value/100 (e.g. 38400 baud = 384)	W
4000 2	Modbus Slave Communication Port Configuration.	Unsigned	1= No parity, 2 Stop bits 2= Even parity, 1 stop bit 3= Odd parity, 1 stop bit	W
4000 3	Product Name (characters 8 & 7).	ASCII	1 to 65,535	W
4000 4	Product Name (characters 6 & 5).	ASCII	1 to 65535 char6: 0x49 = I char5: 0x34 = 4	W
4000 5	Product Name (characters 4 & 3).	ASCII	1 to 65535 char4: 0x42 = B char3: 0x4E = N	W
4000 6	Product Name (characters 2 & 1).	ASCII	1 to 65535	W
4000 7	Product actual firmware version.	Unsigned	1 to 65535 (e.g. 409)	RO
4000 8	Product actual EEPROM version.	Unsigned	1 to 65535 (e.g. 203)	RO
4000 9	System Status 1.	Bit String	[B0-B11, B13-B14]: Reserved B12: CO2 alarm 0 = Normal; 1 = Alarm	RO
400 10	System Status 2.	Bit String	[B0-B11, B13-B14]: Reserved B12: Alarm override 0 = Normal; 1 = Alarm	RO
400 11	Internal Temperature.	Unsigned Scale 100	0 to 5000 Value x 100 (e.g. 23°C = 2300)	RO
400 12	External Temperature.	Signed Scale 100	-4000 to 10000 Value x 100 (e.g. 18°C = 1800)	RO
400 13 - Re	eserved			



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Register Index	Description	Data Type	Range	Writable
400 14	Internal Humidity Internal humidity, reading of the integrated humidity sensor of TRLH or TRLGH. If not available the value will be fixed to 0x7FFF (32767)	Signed Scale 10	0 to 1000 Value x 10 (e.g. 45%RH = 450)	RO
400 15	Input 3 reading, pressure sensor value	Unsigned	0 to 4000 mV	RO
400 16	Pressure input 2 value.	Unsigned	Slave: 0 to 4000 mV	RO
400 17	Analog Input 2 value.	Unsigned Scale 100	Salve: 0 to 1000 Value x 100 (e.g. 3 mV = 300)	RO
400 18	CO2 value in ppm If using TRLG or TRLG and CO2 is in TRL mode, it is the sensor value in ppm. If using Al1 or Al2 and CO2 is set in Analog more, the reading is from the external sensor.	Unsigned Scale 100	100 to reg 400 98 Value x 100 (e.g. 5 ppm = 500)	RO
400 19	Air supply temperature.	Signed Scale 100	-4000 to 10000 Value x 100 (e.g. 5°C = 500)	RO
400 20	Control temperature.	Signed Scale 100	-4000 to 10000 Value x 100 (e.g. 25°C = 2500)	W
400 21	Heating demand for heating ramp 1.	Unsigned Scale 10	0 to 1000 Value x 10 (e.g. 25% = 250)	RO
400 22	Cooling demand for cooling ramp 1.	Unsigned Scale 10	0 to 1000 Value x 10 (e.g. 25% = 250)	RO
400 23	Temperature offset applied on internal temperature.	Signed Scale 100	-500 to 500 Value x 100 (e.g. 0.5°C = 50)	W
400 24	Temperature offset applied on external temperature.	Signed Scale 100	-500 to 500 Value x 100 (e.g. 0.5°C = 50)	W
400 25	Temperature setpoint used during the occupancy period of the day.	Unsigned Scale 10	Range: 400 26 to 400 27 <i>Value x 10</i> (e.g. 20°C = 200)	W
400 26	Minimum temperature setpoint used during the day.	Unsigned Scale 10	Range: 100 to 400 27 <i>Value x 10 (e.g. 10°C = 100)</i>	W
400 27	Maximum temperature setpoint used during the day.	Unsigned Scale 10	Range: 400 26 to 400 <i>Value x 10 (e.g. 40°C = 400)</i>	W
400 28	Cooling setpoint during No Occupancy / Night Set Back	Unsigned Scale 10	Range: 400 29 to 400 <i>Value x 10 (e.g. 22°C = 220)</i>	W
400 29	Heating setpoint during No Occupancy / Night Set Back	Unsigned Scale 10	Range: 100 to 400 28 <i>Value x 10 (e.g. 16°C = 160)</i>	W
400 30	Cooling demand for proportional band 1.	Unsigned Scale 10	5 to 50 Value x 10 (e.g. 0.3°C = 3)	W
400 31	Heating demand for proportional band 1.	Unsigned Scale 10	5 to 50 Value x 10 (e.g. 0.3°C = 3)	W
400 32	Cooling dead band for proportional band 1.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.3°C = 3)	W
400 33	Heating dead band for proportional band 1.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.3°C = 3)	W



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Register Index	Description	Data Type	Range	Writable
400 34 - Re	eserved			
400 35	Night setback override delay in minutes.	Unsigned	0 to 180 minutes	W
400 36	Integral time factor for heating in seconds.	Unsigned	0 to 250 seconds	W
400 37	Cooling anti-cycle delay: delay in minutes before activating or reactivating the cooling contact.	Unsigned	0 to 15 minutes	W
400 38	Floating time 1: Indicates the time in seconds required by the actuator to complete a 90° run.	Unsigned	15 to 250 seconds	W
400 39	Occupancy Delay Mode in minutes	Unsigned	0 to 180 minutes	W
400 40	Cooling demand for cooling ramp 2.	Unsigned Scale 10	0 to 1000 % Value x 10 (e.g. 30% = 300)	RO
400 41	Proportional band for cooling ramp 2	Unsigned Scale 10	5 to 50 Value x 10 (e.g. 0.2°C = 2)	W
400 42	Dead band for cooling ramp 2.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.2°C = 2)	W
400 43	Heating demand for heating ramp 2.	Unsigned Scale 10	0 to 1000 % Value x 10 (e.g. 30% = 300)	W
400 44	Proportional band for heating ramp 2.	Unsigned Scale 10	5 to 50 Value x 10 (e.g. 0.2°C = 2)	W
400 45	Dead band for heating ramp 2.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.2°C = 2)	W
400 46 to 4	100 49 - Reserved			
400 50	AO2 min Vdc: minimum* voltage of analog output 2.	Unsigned Scale 10	Range: 0 to reg. 400 52 <i>Value x 10 (e.g. 2 Volts = 20)</i>	W
400 51 – R	eserved			
400 52	AO2 max Vdc: maximum* voltage of analog output 2.	Unsigned Scale 10	Range: reg. 400 50 to 100 <i>Value x 10 (e.g. 10 Volts = 100)</i>	W
maximum			nand. The minimum voltage is always applied to the eat applications, we recommend to leave the minimu	
400 53	Cfg_Pressure1NumFilter	Unsigned	Master: 1 to 10 seconds	W
400 54	Cfg_AirFlowKFactor1	Unsigned	Master: Range: 100 to 9995 CFM	W
400 55	Minimum air flow for cooling.	Unsigned	Range: 0 or (12.7%) Kfac to reg 400 56 CFM	W
400 56	Maximum air flow for cooling.	Unsigned	Range: reg 400 55 to reg 400 54 CFM	W
400 57	Minimum air flow for heating.	Unsigned	Range: 0 or (12.7%) Kfac to reg 400 58 CFM	W
400 58	Maximum air flow for heating.	Unsigned	Range: reg 400 57 to reg 400 54 CFM	W
400 59 - Re	eserved			
40060	Actual air flow 1 converted from delta	Unsigned	Master: Range: 0 to reg 400 54 CFM	RO
400 60	pressure sensor.			



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Register Index	Description	Data Type	Range	Writable
400 62	Configuration value for Air Flow 1 Max used during airflow balancing sequence. Use to do Kfactor calculation. Refer to EVCB-Airflow Balance Instructions.	Unsigned	Master: Range: 0 to 9999 CFM AirFlow Bal Mode (Reg. 131) must be >= 3 (Maximum Flow)	W
400 63	Motor 2 position	Unsigned	Slave: 0-100%	W
400 64	Analog output 2 value.	Unsigned Scale 10	Unit: Volt, Range: reg 400 50 to reg 400 52 <i>Value x 10 (e.g. 5 Volts = 50)</i>	W
400 65	Percentage of demand to close TRIAC output 1.	Unsigned	15 to 80%	W
400 66	Percentage of demand to close TRIAC output 2.	Unsigned	15 to 80%	W
400 67 to 4	00 67 - Reserved			
400 69	Percentage of demand to open TRIAC output 1.	Unsigned	0 to reg 400 65- 4%	W
400 70	Percentage of demand to open TRIAC output 2.	Unsigned	0 to reg 400 65 -4%	W
400 71 to 4	.00 72 - Reserved			
400 73	Integral time factor for cooling in seconds.	Unsigned	0 to 250 seconds	W
400 74	Motor 1 position.	Unsigned	Master: 0 to 100%	RO
400 75 to 4	00 80 - Reserved			RO
400 81	Air flow 1 offset calibration. Refer to EVCB-Airflow Balance Instructions.	Signed	Master: -500 to 500 CFM AirFlow Bal Mode (Reg. 131) must be = 1 (Close)	W
400 82 to 4	0083 – Reserved			RO
400 84	Configuration value for Air Flow 1 Min used during airflow balancing sequence. Refer to EVCB-Airflow Balance Instructions.	Unsigned	Master: Range: 0 to 9999 CFM	W
400 85 to 4	0088 - Reserved			RO
400 89	Cfg_AirFlowKFactor2	Unsigned	Slave: Range: 100 to 9995 CFM	W
400 90	Actual air flow 2 converted from delta pressure sensor.	Unsigned	Slave: Range: 0 to reg 400 89 CFM	RO
400 91	Air flow setpoint 2	Unsigned	Slave: Range: 0 to 9999 CFM	RO
400 92	Air flow 2 offset calibration. Refer to EVCB-Airflow Balance Instructions.	Signed	Slave: -500 to 500 CFM AirFlow Bal Mode (Reg. 131) must be = 1 (Close)	W
400 93	Configuration value for Air Flow 2 Min used during airflow balancing sequence. Use to do minimum flow factor calculation. Refer to EVCB-Airflow Balance Instructions.	Unsigned	Slave: Range: 0 to 9999 CFM AirFlow Bal Mode (Reg. 131) must be = 2 (Minimum Flow)	W
400 94	Configuration value for Air Flow 2 Max used during airflow balancing sequence. Use to do Kfactor calculation. Refer to EVCB-Airflow Balance Instructions.	Unsigned	Slave: Range: 0 to 9999 CFM AirFlow Bal Mode (Reg. 131) must be >= 3 (Maximum Flow)	W
400 95	Cfg_Pressure2NumFilter	Unsigned	Slave: 1 to 10 seconds	W
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Register Index	Description	Data Type	Ra	ange	Writable
400 96	Network fallback timeout Present Value in minutes.	Unsigned	0 to 60 minutes		W
400 97	Reserved				RO
400 98	Maximum range of the CO2 sensor connected to Al1 or Al2.	Unsigned	100 to 5000 PPM		W
400 99	Maximum concentration of CO2 before the EVC activates an alarm.	Unsigned	Range: 100 to the greate 2000 and reg 400 98	er ppm value between	W
40 100	System Option 1.	Bit String	B3, B5, B13-B14: Reserved B0: Tstat temperature units 0 = Celsius 1 = Fahrenheit B1: Modbus temperature units 0 = Celsius 1 = Fahrenheit B2: Temperature setpoint lock 0 = Unlocked 1 = Locked B4: TO1/TO2 floating direction 0 = Direct 1 = Reverse B6: Onboard motor 1 direction Master 0 = Direct 1 = Reverse B7: Freeze protection 0 = Disabled 1 = Enabled	B8: User system off mode 0 = User can set Tstat to OFF 1 = User cannot set Tstat OFF B9: Keypad bottom left lock 0 = Unlocked 1 = Locked B10:Keypad upper left lock 0 = Unlocked 1 = Locked B11: Keypad arrows lock 0 = Unlocked 1 = Locked B12: Program lock 0 = Unlocked 1 = Locked B15: Schedule 0 = Disabled 1 = Enabled	W
40 101	System Option 2. Notes B14: Applies only if DI2 is in OverHeat or Override.	Bit String	B0, B8-9, B11-13, B15: Reserved B1: Cfg_Pressure 2 Option (slave) 0 = Local 1 = Total B2: Auto baud rate detection 0 = Enabled 1 = Disabled B3: Night setback mode 0 = Tstat ON 1 = Tstat OFF	B4: Cfg_Motor 2 direction (slave) 0 = Direct; 1 = Reverse B5: AO2 direction 0 = Direct; 1 = Reverse B6: TO1 direction 0 = Direct; 1 = Reverse B7: TO2 direction 0 = Direct; 1 = Reverse B10: Display RH 0 = No; 1 = Yes B14: DI 2 Contact 0: NO; 1: NC	W



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Register Index	Description	Data Type	Range	Writable
40 102 - Re	eserved			
40 103	System command status.	Unsigned	0 = No Command 1 = AirFlow Balancing 1 (0=disabled 1=enabled) 4 = AirFlow Balancing 2 (0=disabled 1=enabled) 64 = Cfg_Press1 Calib (0=no 1=yes) 128 = Cfg_Press2 CalibLock (0=lock 1=unlock)	w
40 104	TO OnOff.	Unsigned	1 = TO1 OnOff 2 = TO2 OnOff	RO
40 105	Occupancy or night setback mode commands.	Unsigned	1 = Locally 2 = Off 3 = Occupancy 4 = NoOccupancy 5 = Day 6 = Night	w
40 106	Status of digital input 1.	Unsigned	0 = Open 1 = Close	RO
40 107 - Re	eserved			
40 108	User System Control Mode.	Unsigned	1 = AUTO 2 = HEAT 3 = COOL 4 = OFF	W
40 109	Sets the permissions or restrictions to change the system control mode by the user.	Unsigned	1 = AUTO 2 = HEAT 3 = COOL 4 = COOL-HEAT 5 = AUTO-LOCK	W
40 110	Indicates the status of the Night Setback mode.	Unsigned	1 = Day 2 = Night 3 = Derogation	RO
40111	Configuration of DI1 mode. Night setback or no occupancy status.	Unsigned	1=Off 2= Occupancy NO 3= Occupancy NC 4= Night Set Back NO 5= Night Set Back NC	w
40 112	Cfg_Universal Input Al2 Type	Unsigned	1 = OFF 2 = ETS 3 = CO2 4 = AST	W
40 113	Occupancy status of the zone.	Unsigned	1 = No Occupancy 2 = Occupancy 3 = Derogation	RO
40 114 - Re	eserved			
40 115	AO2: Analog output 2 control ramp	Unsigned	1 = OFF 4 = HR1 (heat ramp 1) 2 = CR1 (cool ramp 1) 5 = HR2 (heat ramp 2) 3 = CR2 (cool ramp 2) 6 = CO2 7 - 12 = reserved	W
40 116	TO1: Configuration of the ramp used to modulate (pulse or floating) or activate/deactivate (On/Off) TO1 based on demand.	Unsigned	1 = OFF 4 = HR1 (heat ramp 1) 2 = CR1 (cool ramp 1) 5 = HR2 (heat ramp 2) 3 = CR2 (cool ramp 2) 6 = CO2 7 - 12 = reserved	W
40117	TO2: Configuration of the ramp used to modulate (pulse or floating) or activate/deactivate (On/Off) TO2 based on demand.	Unsigned	1 = OFF 4 = HR1 (heat ramp 1) 2 = CR1 (cool ramp 1) 5 = HR2 (heat ramp 2) 3 = CR2 (cool ramp 2) 6 = CO2 7 - 12 = reserved	W



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Register Index	Description	Data Type	Range	Writable
40 118 to 4	.0119 - Reserved	<u> </u>		
40 120	TO1: Signal output type for TRIAC output 1.	Unsigned	3 = Pulsing 4 = On_Off 5 = Floating	W
40 121	TO2: Signal output type for TRIAC output 2.	Unsigned	3 = Pulsing 4 = On_Off	W
40 122 to 4	0 124 - Reserved	ļ	_	
40 125	Motor ramp: Configuration of the ramp used to modulate the actuator based on demand.	Unsigned	2 = CR1 (cooling ramp 1) 4 = HR1 (heating ramp 1)	W
40 128 to 4	0 128 - Reserved			
40 129	Configuration of DI2 mode.	Unsigned	1=Off 2=Override 3=OverHeat1 4=OverHeat2 5=OverHeatAll	W
40 130	Selected temperature control source (in Programming mode).	Unsigned	1 = Internal Temperature 2 = External Temperature 3 = Remote Temperature	W
40 131	Airflow 1 balance mode, enter the balancing mode to adjust air flow factor.	Unsigned	Master: 1 = Close 2 = Minimum Flow 3 = Maximum Flow 4 = Full Open	W
40 132	Airflow 2 balance mode, enter the balancing mode to adjust air flow factor.	Unsigned	Slave: 1 = Close 2 = Minimum Flow 3 = Maximum Flow 4 = Full Open	W
40 133	Configuration to set the motor position in night setback mode.	Unsigned	1 = Auto 2 = Open	W
40 134	Digital input 2 delay in seconds.	Unsigned	0 to 3600 seconds	W
40 135 to 4	0 135 - Reserved			<u> </u>
40 138	Airflow Hysteresis Stop in percentage.	Unsigned	1 to 100%	W
40 139	Airflow Hysteresis Start in percentage.	Unsigned	reg 40 138 to 100%	W
40 140	Airflow scale.	Unsigned	1 = Scale1, 2 = Scale10, 3 = Scale100	W
40 141 to 4	.0144 - Reserved	<u> </u>		
40 145	CL_HT SwitchTimer, waiting time before switching between the heating and cooling modes.	Unsigned	0 to 120 minutes	w
40 146	CL_HT SwitchTimerCount, countdown to indicate the swap between heating and cooling modes.	Unsigned	0 to 4,294,967,295 seconds	RO
40 147	FloatingTO1/TO2, TRIAC output 1 or 2 when set to floating, indicates the floating signal demand.	Unsigned Scale 10	0 to 1000% Value x 10 (e.g. 15% =150)	RO
40 148 - Re	eserved			
40 149	TO1 Pulsing, TRIAC output 1 when set to Pulsed, indicates the pulse signal demand.	Unsigned Scale 10	0 to 1000% Value x 10 (e.g. 15% =150)	RO



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Register Index	Description	Data Type	Range	Writable
40 150	TO2 Pulsing, TRIAC output 2 when set to Pulsed, indicates the pulse signal demand.	Unsigned Scale 10	0 to 1000% Value x 10 (e.g. 15% =150)	RO
40 151 to 4	0152 - Reserved			
40 153	Over heat status.	Unsigned	1 = OverHeatNormal 2 = OverHeat1 3 = OverHeat2 4 = OverHeatAll	RO
40 154	Configuration to override the motor 1 position.	Unsigned	Master: 1 = Auto 2 = Open 3 = Close 4 = AirFlowCoolMin 5 = AirFlowCoolMax	W
40 155	Information displayed on the TRL.	Unsigned	1 = Temp Demand 2 = Setpoint Demand 3 = Temp 4 = Setpoint 5 = Off	w
40 156	Status of digital input 2.	Unsigned	0 = Open 1 = Close	RO
40 157	Cfg_Input3 Minimum Reading, this setting represents the deadband of the pressure sensor in mV.	Unsigned	10 to 180 mV	W
40 158	System Options 3	Bit String	[B0 − B1], [B4, B6 − B15]: Reserved B2: CO₂ Display 0 = No; 1 = Yes B3: CO₂ Control Source 0 = Analog; 1 = TRLG B5: Constant Flow Options 0 = No; 1 = Yes	W
40 159	System Options 4	Bit String	[B0 – B15]: Reserved	RO
40 160	Internal CO2, reading of the integrated CO2 sensor of TRLG or TRLGH. If not available the value will be fixed to 0x7FFF (32767)	Unsigned	Range: 0 to 2000 ppm	RO
40 161	Motor 2 Position Override	Unsigned	Slave: 1 = Auto 2 = Open 3 = Close 4 = AirFlowCoolMin 5 = AirFlowCoolMax	W



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Register Index	Description	Data Type	Range	Writable
40 162	Cfg_MixAirDeadBand	Unsigned	Range: 0 - dB Cool 1 or dB Heat 1 (the lower one)	W
40 163	Occupancy minimum time in minutes.	Unsigned	0 to 240 minutes	W

Notes		



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